

FUZZY LOGIC CONTROL BASED DC – DC CONVERTER FOR FUEL CELL APPLICATION

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ABSTRACT

The power required day to day highly, the non conventional energy are available,(solar, wind) this type of energy's depended only weather condition, but Fuel Cell are independent sources, the proposed converter Fuzzy logic control based DC-DC converter for fuel cell application, a control strategy that combines the use of a dc-dc boost converter, fuzzy logic control, It is believed that this research will lead to improvement in the efficiency of DC DC Converter fuel cell.

Keywords—Fuel Cell, DC-DC converter, Efficiency.

1. INTRODUCTION

Implementing the optimal maximum affiance and implementation and suitability and compatibility to the end user's requirements [1],[2]. Different MPPT techniques have been used for different setups, depending on the task being Performed [2]–[5]. Ongoing research addressing these issues [6]–[8] and state-of-the-art technologies is emerging [9]–[13]. Power harnessed from solar photovoltaic (PV) systems has not gained commercial status as its counterpart non renewable power generation technologies [14]. As stated in the survey and comparison of various MPPT techniques in [1], “These methods vary in complexity, sensors required, convergence speed, cost, and range of Effectiveness, implementation hardware and other factors.” As a matter of fact, these are the basic criterion for selecting an MPPT technique. The functioning and performance of more than 90 MPPT methods are discussed and compared in [1]. A general short-coming of nearly all of the known MPPT techniques is the in- capability of handling uncertain weather conditions due to the assumption of standard solar irradiance and ambient temperature values. To address these issues, a dynamic model of Fuel Cell considering the variability of irradiance and ambient temperature on a real-time basis is reported. The dynamic model is simulated and verified, using the data acquisition system and has achieved model accuracy of 97.97%. The maximum power point varies over the Whole day with the variation of the fuel Cell chemical conditions. In order to track it exactly, an appropriate value of load has to be matched. In this work, the dynamic Fuel model developed earlier it is used in conjunction with a dc-dc boost converter for harnessing the instantaneous maximum output power through real-time robust load matching. The duty cycle

can be estimated using proportional integral (PI) controller as where and are the proportional and integral constants. However, the conventional PI controller has the major drawback of control chattering; i.e., the controller output is a discontinuous high-frequency switching signal. This makes the PI controller not suitable for this application because of the continuous nature of variables and high-frequency switching requirement of the dc-dc converter. Simulation results in MATLAB/Simulink environment, for fixed and variable loads, are presented to demonstrate the effectiveness of the proposed MQBGA-based FLC control scheme. This manuscript is divided into six sections. Real-time robust load matching for a fuel cell system is outlined in this Section. In this section the control strategy is proposed. Modeling and the FLC and the Fuel Cell is achieved through the model developed earlier and the desired voltage is achieved by the boosted output voltage of the dc-dc converter. The overall supervisory control for real-time robust load matching and control of duty cycle of the dc-dc converter is achieved through FLC. Basic of FLC is described in. Through the processing of heuristic information, an FLC interpolate among the consequent of all the rules according to their firing strength. Therefore, an FLC can be seen as multiple PID/PI controllers with smooth interpolation capability, without chattering phenomena for real-time applications. A suitable learning mechanism of the knowledge base of FLC and the tuning of the controller parameters are required to achieve the desired real-time performance. Learning mechanisms such as genetic algorithm (GA) can be implemented to tune the control parameters in such cases. GA performs an intelligent search for a solution from a very large

number of possible solutions. Hence, the chances of converging to local minima have been reduced and global optimum can be approached with higher probability. Thus, it has been tried to enhance the performance of FLC for the proper load matching of FC module for standalone application.

2. CONTROL STRATEGY

The overall objective is to make the output power at the load level equal to the harvestable maximum power by the FC model, while maintaining the dc-dc booster voltage at a desired constant level. To harness the instantaneous maximum power, the MPPT model estimates the load seen by the Fuel Cell module. The ambient and FC module temperature are found. The value of the load computed by the MPPT model fluctuates with the solar FC module's temperature dynamics, ambient temperature. The load seen by the FC module not only gets affected by the above-mentioned factors, but also by the duty cycle of the boost converter. During one complete control cycle, the maximum voltage, current, maximum power, and the maximum possible load are calculated through the MPPT model. The output power available at the load is calculated and compared with the maximum power. The actual load matching condition can be expressed as follows. Represents the proposed scheme for maximum power harvesting at MPP from a standalone FC system under uncertain environmental conditions. The value of e is computed by the MPPT model, and the constant dc-dc converter's output voltage to be achieved is given in (3) in terms of the output voltage of the FC module the inputs to the FC module and the MPPT model are real-time ambient temperature. The instantaneous boost output voltage of the dc-dc converter is compared with the reference voltage. The error in voltage is input as error and change in voltage error. Finally it calculates the temperature and output voltage of FC and finally these inputs are given to DC – DC converter Topology circuits and it finds maximum power from the FC module. In future works it designs the DC DC boost converter. These diagrams mention only FLC inputs.

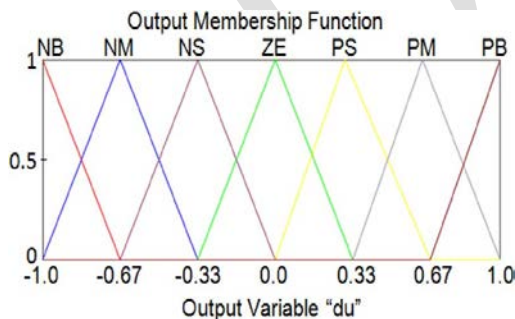


Fig 1. Gaussian membership function

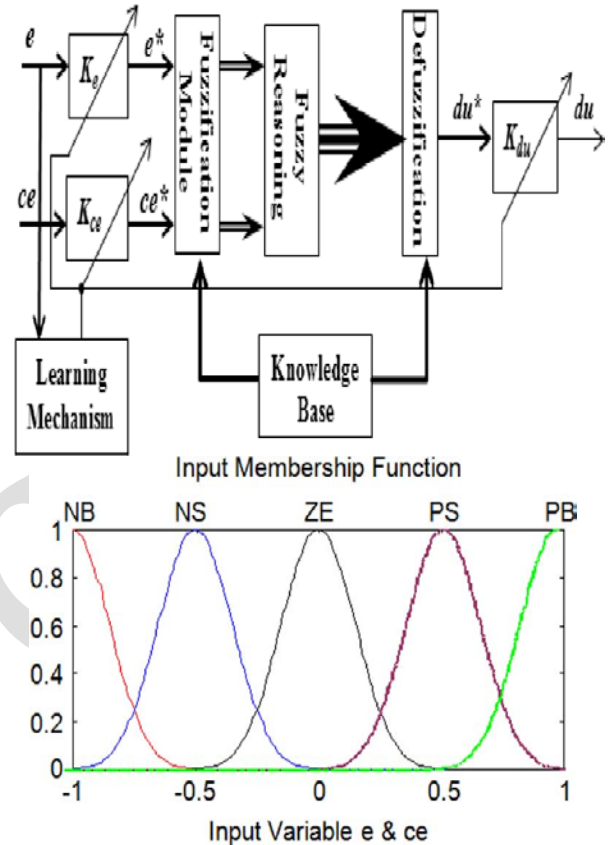


Fig 2. Gaussian membership function for inputs

e^* \ ce^*	NB	NS	ZE	PS	PB
NB	1. NB	2. NB	3. NM	4. NS	5. ZE
NS	6. NB	7. NM	8. NS	9. ZE	10. PS
ZE	11. NM	12. NS	13. ZE	14. PS	15. PM
PS	16. NS	17. ZE	18. PS	19. PM	20. PB
PB	21. ZE	22. PS	23. PM	24. PB	25. PB

Fig 3. Membership function for inputs tables

3. CONCLUSION

This Proposed Converter topology are find out the six set of values the following words are mention it NB,NM,NS,ZE,PS,PM, and PB. In Future works using these types of FLC is giving the gate pulse for converter circuit and find maximum efficiency. These types of converters are reducing the switching loss.

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